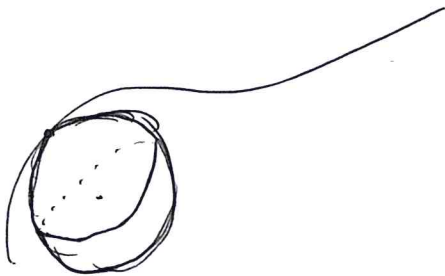


Tutorial 2 DG

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1. Osculating sphere (Thm 2.10 in the Textbook)

In \mathbb{R}^3 ,



Thm:

$C =$ Frenet curve in \mathbb{R}^3 with $\tau(s_0) \neq 0$. (parametrized by arc-length)

The sphere with center $C(s_0) + \frac{1}{K(s_0)} e_2(s_0) - \frac{K'(s_0)}{\tau(s_0) K^2(s_0)} e_3(s_0)$ passing through $C(s_0)$

has a point of contact with the curve $C(s)$ at the point s_0 of 3rd order. This sphere is uniquely determined by these properties and is called the osculating sphere.

Pf:

Assume centre $m(s_0) = C(s_0) + \alpha e_1(s_0) + \beta e_2(s_0) + \gamma e_3(s_0)$,

α, β, γ are to be determined.

Consider

$$r(s) = \langle m - c(s), m - c(s) \rangle, \quad m = m(s_0)$$

$$r' = -2 \langle m - c(s), c'(s) \rangle$$

$$r'' = -2 \langle m - c(s), c''(s) \rangle + 2 \langle c'(s), c'(s) \rangle$$

$$r''' = -2 \langle m - c(s), c'''(s) \rangle + 2 \langle c'(s), c''(s) \rangle \\ + 4 \langle c'(s), c''(s) \rangle$$

$$= -2 \langle m - c(s), c'''(s) \rangle + 6 \langle c'(s), c''(s) \rangle$$

Note that $\langle c', c'' \rangle = 0$, $r''' = -2 \langle m - c(s), c'''(s) \rangle$.

The optimal contact of the sphere with $c(s)$ means that as many derivatives of $r(s)$ as possible vanish at $s = s_0$. i.e

$$r'(s_0) = 0 \Leftrightarrow \langle m - c(s_0), c'(s_0) \rangle = 0$$

$$\Leftrightarrow \langle m - c(s_0), e_1(s_0) \rangle = 0$$

$$\Leftrightarrow \alpha = 0.$$

$$r''(s_0) = 0 \Leftrightarrow \langle m - c(s_0), c''(s_0) \rangle - \langle c'(s_0), c'(s_0) \rangle = 0$$

$$e_2 = \frac{c''}{k}$$

$$\Leftrightarrow \langle \beta e_2 + r e_3, k e_2 \rangle = 1$$

$$\Leftrightarrow \beta = \frac{1}{k(s_0)}$$

$$r'''(s_0) = 0 \Leftrightarrow \langle m - c(s_0), c'''(s_0) \rangle = 0$$

$$\Leftrightarrow \langle \frac{1}{k} e_2 + r e_3, k' e_2 + k(-k e_1 + \tau e_3) \rangle = 0$$

$$\Leftrightarrow \frac{k'}{k} + r k \tau = 0$$

$$\Leftrightarrow r = -\frac{k'(s_0)}{k^2(s_0)\tau(s_0)}$$

$$\text{So } m(s_0) = c(s_0) + \frac{1}{k(s_0)} e_2(s_0) - \frac{k'(s_0)}{k^2(s_0)\tau(s_0)} e_3(s_0)$$

$$\text{Centre} = m(s_0), \text{ Radius} = \sqrt{\frac{1}{k^2(s_0)} + \frac{k'^2(s_0)}{k^4(s_0)\tau^2(s_0)}} \Rightarrow \text{Sphere } \mathcal{S}_{s_0}$$

pass through $c(s_0)$, $r'(s_0) = 0 \Rightarrow c'(s_0)$ is incident to

tangent plane of \mathcal{S}_{s_0} at s_0 , \exists curve $\gamma(s)$ on \mathcal{S}_{s_0} s.t

$$\gamma(s_0) = c(s_0), \gamma'(s_0) = c'(s_0)$$

$$r''(s_0) = 0 \Rightarrow \delta''(s_0) = c''(s_0)$$

$$r'''(s_0) = 0 \Rightarrow \delta'''(s_0) = c'''(s_0).$$

s_0 we say this sphere has a pt of contact with the curve $c(s)$ at s_0 of 3rd order.

2. Slope Lines (Thm 2.11 in the Textbook)

For a Frenet curve in \mathbb{R}^3 , the following conditions are equivalent:

(i) $\exists v \in \mathbb{R}^3 \setminus \{0\}$ with the property that $\langle e_1, v \rangle$ is constant.

(ii) $\frac{\tau}{\kappa}$ is constant.

We call such curve slope line.

Pf: (i) \Rightarrow (ii)

We may write $\langle e_1, v \rangle = |v| \cos \theta$ for some constant θ

$$\text{Differentiation} \Rightarrow 0 = \langle e_1', v \rangle$$

$$= k \langle e_2, v \rangle$$

$$\Rightarrow \langle e_2, v \rangle = 0 \text{ since } k \neq 0$$

$$\Rightarrow v = \cancel{\langle v, e_1 \rangle e_1} + \langle v, e_3 \rangle e_3$$

$$= |v| \cos \theta e_1 + |v| \sin \theta e_3 \quad \left(\begin{array}{l} \text{change } \theta \text{ to} \\ -\theta \text{ if necessary} \end{array} \right)$$

$$\text{Differentiation} \Rightarrow$$

$$0 = |v| \cos \theta e_1' + |v| \sin \theta e_3'$$

$$\Rightarrow$$

$$0 = \cos \theta k e_2 + \sin \theta (-\tau e_2)$$

$$= (k \cos \theta - \tau \sin \theta) e_2$$

$$\Rightarrow k \cos \theta - \tau \sin \theta = 0$$

$$\Rightarrow \frac{\tau}{k} = \cot \theta \quad (\theta \neq 0 \text{ otherwise } k=0 \text{ or } \tau=0)$$

$$\text{(ii)} \Rightarrow \text{(i)} \quad \text{If } \frac{\tau}{k} = \text{constant}, \exists \theta \text{ s.t.}$$

$$\frac{\tau}{k} = \cot \theta$$

$$\text{Def } V = \cos \theta e_1 + \sin \theta e_3$$

$$\begin{aligned} V' &= \cos \theta e_1' + \sin \theta e_3' \\ &= (k \cos \theta - \tau \sin \theta) e_2 \\ &= 0 \end{aligned}$$

$$\langle e_1, v \rangle = \cos \theta = \text{constant!}$$

□

Rmk: Helix is an example.

Please also read Thm 2-11 in the textbook since I provide a different proof.

3. Suggested exercise 3 in HW1.

The Frenet two-frame of a plane curve with given curvature function $k(s)$ can be described by the exponential series for the matrix

$$\begin{pmatrix} 0 & \int_0^s k(t) dt \\ -\int_0^s k(t) dt & 0 \end{pmatrix}$$

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$$\text{i.e. } \begin{pmatrix} e_1(s) \\ e_2(s) \end{pmatrix} = \sum_{i=0}^{\infty} \frac{1}{i!} \begin{pmatrix} 0 & \int_0^s k(t) dt \\ -\int_0^s k(t) dt & 0 \end{pmatrix}^i$$

Pf: Given a curvature function $k(s)$, assume

$$e_1 = (\cos(\alpha(s)), \sin(\alpha(s)))$$

$$\text{then } e_2 = (-\sin(\alpha(s)), \cos(\alpha(s)))$$

$$k e_2 = e_1' = \alpha' (-\sin(\alpha(s)), \cos(\alpha(s))) = \alpha' e_2$$

$$\Rightarrow k = \alpha'$$

$$\Rightarrow \alpha(s) = \int_0^s k(t) dt \quad \text{if } \alpha(0) = 0 \text{ i.e. } e_1(0) = (1, 0)$$

$$\Rightarrow e_1 = (\cos(\int_0^s k), \sin(\int_0^s k))$$

$$e_2 = (-\sin(\int_0^s k), \cos(\int_0^s k))$$

i.e

$$\begin{pmatrix} \cos X & \sin X \\ -\sin X & \cos X \end{pmatrix} = \sum_{n=0}^{\infty} \frac{1}{n!} \begin{pmatrix} 0 & x \\ -x & 0 \end{pmatrix}^n$$

(note that $\begin{pmatrix} 0 & +x \\ -x & 0 \end{pmatrix}^0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$),

$$\cos X = 1 - \frac{x^2}{2} + \frac{x^4}{4!} - \dots$$

$$\sin X = x - \frac{x^3}{6} + \frac{x^5}{5!} - \dots$$